



# Automotive-Grade, Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection

#### **Description**

The SC8450 series is a new member of SENK SEMI.'s fully integrated current sensor product line, With the industry's first packaging technology, current wire impedance as low as  $0.24m\Omega$  is achieved on a wide-body SOP-16 package of 10mm\*11mm\*2.3mm, It can be used in power systems requiring measurements up to 150A. Suitable for customers for batch automatic patch production, it is the best solution for small volume, high current applications.

The SC8450 series is an isolated current detection chip that operates on the open-loop Hall sensor detection principle. By introducing the current conductor on the high voltage side into the package, based on the magnetic effect of the current, the equal-proportional magnetic field generated around the measured conductor is induced by the magnetic sensor of the built-in chip and converted into the equal-proportional voltage signal that can be processed. The voltage signal is read and amplified by the built-in high-precision ADC, and with digital calibration technology, environmental variables such as temperature, noise, hysteresis, nonlinearity and so on are removed, and the final output voltage value is nearly ideal ratio with the measured current value, so as to achieve isolated current measurement.

The SC8450 series adds built-in and adjustable fault monitoring with an open drain output, and its built-in FLAG\_F uses a built-in fixed fault threshold without requiring any additional components, Built-in protection response of less than 2uS can be achieved. Very suitable for severe short-circuit fault detection. FLAG\_S supports users to set their own fault thresholds using peripheral divider resistors, And the current pulse shielding setting can ignore the interference in the application to prevent false alarms, very suitable for mild overcurrent detection and feedback peak setting. This function is flexible in fault detection and greatly simplifies the circuit board application layout.

#### **Features**

- AEC-Q100 automotive qualified
- Isolated measurement, isolated voltage up to 4.8kv @50HZ,1min
- Can measure DC, AC current
- Signal detection bandwidth up to 240khz
- Lowest current wire impedance:0.24mΩ
- Differential sensing technology has high anti-interference ability to the external environment
- User configurable fault detection function

FLAG\_F: Built-in protection, suitable for severe short circuit detection

FLAG\_S: Adjustable protection for overload detection and user configuration

- Static voltage output support: 0.1VCC/0.5VCC
- Response time as low as 2uS
- Wide range of measured current: 0A~150A
- High accuracy: Accuracy error < 1% at 25°C

Operating temperature: Accuracy error<3%

- Strong driving capability, supporting output ports with loads as low as 2kΩ
- Independent intellectual property rights, no technology dependence

Isolation safety certification:



#### Package

◆ Top View:

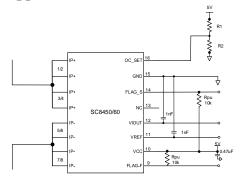
(mark information is not subject to this rule)



Current Path view:



# **Typical Application**





#### **Order information**

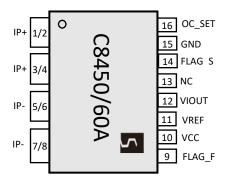
Part Number	Characteristics code	Qualified level	Temp Range	Packing	Current IP Range (A)	0AOutput*1 (V)	Sensitivity *2 (mV/A)	Supply voltag (V)
SC8450A1FT-100B3					± 100	0.5Vcc	13.2	
SC8450A1FT-150B3		Grade 1 (Aec-Q100)	E( 40, 1259C)	T (Reel, 1000 pieces/reel)	± 150	0.5Vcc	8.8	3.3
SC8450A1FT-50F3					± 50	1.65	26.4	3.3
SC8450A1FB-150F3	A				± 150	1.65	8.8	
SC8460A1FT-100B5	A		F(-40~123 C)		± 100	0.5Vcc	20	5.0
SC8460A1FT-150B5					± 150	0.5Vcc	13.33	
SC8460A1FT-50F5					± 50	2.5	40	5.0
SC8460A1FT-150F5					± 150	2.5	13.33	

Note1: Type B and F Reference output types when IP=0A

В	When IP has no current, VIOUT@0A=VREF=0.5VCC, suitable for bidirectional current detection, zero point and sensitivity
ь	change with VCC ratio
Е	When there is no current in the IP, VIOUT@0A=VREF=2.5V/1.65V, which is suitable for bidirectional current sensing, and the
Г	zero point and sensitivity vary with VCC ratio

Note2: Factory shipment default Mask=0uS, this function is turned off, if the customer needs to turn on the function, you can ask our FAE/ agent

# Pin Configuration(Top view)

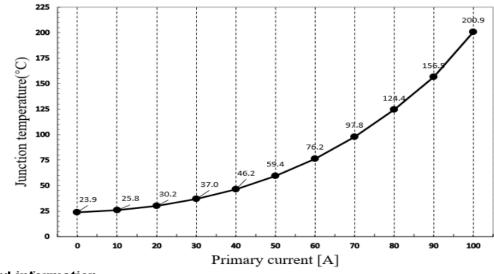


Pin number	Pin Name	Description
1/2/3/4	IP+	Terminals for current being sampled; fused internally, support connect to 1/2/3/4
5/6/7/8	IP-	Terminals for current being sampled; fused internally, support connect to 5/6/7/8
9	FLAG_F	Built-in fault output, built-in overcurrent threshold multiple
10	VCC	Device power supply terminal
11	VREF	Reference terminal, supporting input and output. Specifically define Note 1 of the above ordering information VIOUT= Vref (IP=0A)
12	VIOUT	Analog output signal, VIOUT=IP*Sens+Vref
13	NC	No connection
14	FLAG_S	Adjustable fault output
15	GND	Signal Ground terminal
16	OC_SET	External fault threshold voltage (support NC)



#### Thermal Rise vs. Primary Current

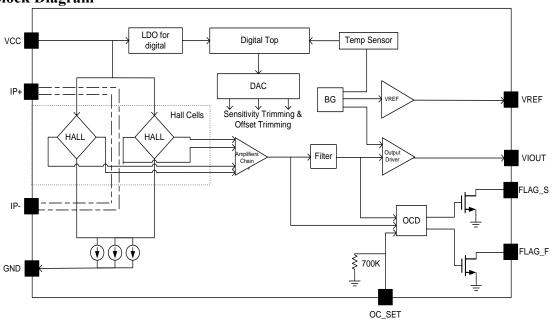
Typical Plastic package temperature[°C] of SC8450/60 vs Primary current [A] based on Demo Board.



#### **Demo Board information**

	DEMO	Units
PCB Layer Number	2	
PCB Copper layer thickness	2	Oz
Total Copper size connected to Primary pins(including all layers)	350	$mm^2$
PCB Board Thickness	1.6	mm

# **Functional Block Diagram**





#### **Absolute Maximum Ratings**

Absolute maximum rating is the operating limit of a device, exceeding which may cause device damage. Frequent operation outside

this value range may affect device reliability.

Symbol	Characteristic	Notes	Ratings	Units
Vcc	Supply voltage		6	V
$V_{RCC}$	Reverse Supply Voltage		-0.1	V
V <sub>IOUT</sub>	Output Voltage		6	V
$V_{RIOUT}$	Reverse Output Voltage	VIOUT, VREF	-0.1	V
V <sub>FLAG</sub>	Forward Output Voltage	li-abla to the ELACflow for ation	6	V
V <sub>RFLAG</sub>	Reverse Output Voltage	applicable to the FLAG overflow function	-0.1	V
V <sub>OC_SET</sub>	Forward Output Voltage	li-abla to the OC SET formation	6	V
V <sub>ROC_SET</sub>	Reverse Output Voltage	applicable to the OC_SET function	-0.1	V
		Range G	-40~150	
TA	Operating Temperature	perating Temperature Range F		°C
		Range E	-40~85	
T <sub>J</sub> (max)	Maximum Junction Temperature		165	°C
T <sub>stg</sub>	Storage Temperature		-65~170	°C
Iout(Source)	Output Current Source	Shorted Output-to-Ground Current	30	mA
I <sub>OUT(Sink)</sub>	Output Current Sink	Shorted Output-to-VCC Current	30	mA
I <sub>REF</sub> (Source)	Vref Current Source	Shorted Vref-to-Ground Current	15	mA
I <sub>REF(Sink)</sub>	Vref Current Sink	Shorted Vref-to-VCC Current	15	mA
IP <sub>max</sub>	Maximum Continuing IP Current	Based on SENK's Demo Test Board	100	A
IPover	Transient Over Current at Ambient Temperature	Based on SENK's Demo Test Board, 1pulse, 100ms, 1% Duty Cycle	400	A
ESD	HBM mode		4	kV

#### **Isolation Characteristics**

Symbol	Characteristic	Notes	Ratings	Units
V <sub>ISO</sub>	RMS voltage for AC insulation test,50Hz,1min	Agency type-tested for 60 seconds per UL60950-1	4800	Vrms
$V_{\mathrm{WVRI}}$	Working Voltage for Basic Isolation	Maximum working voltage according to UL60950-1	1500	V <sub>Peak</sub>
Dcl	Clearance	Minimum distance through air from IP leads to signal leads	8	mm
Dcr	Creepage distance	Minimum distance along package body from IP leads to signal leads	8	mm
CTI	Comparative trackong index	the electrical breakdown (tracking) properties of an insulating material	600	V
V <sub>IOSM</sub>	Maximum surge isolation voltage	Tested $\pm 5$ pulses at 2/minute in compliance to IEC 61000-4-5 1.2 $\mu$ s (rise) / 50 $\mu$ s (width).	10	kV
I <sub>IOSM</sub>	Maximum Transient impulse current	Tested ±5 pulses at 3/minute with 8 μs (rise) / 20 μs (width)	20	kA

Note 1: Meet the safety certification of UL60950-1 and CB62368-1

**Reference application Specification** 

Symbol	Description	Min	Тур	Max	Unit
Cvcc	The filter capacitor of power supply is connected between VCC and GND	0.1	0.47		uF
CVIOUT	The filter capacitor of Output is connected between Vout and GND		1		nF
CVREF	The filter capacitor of Output is connected between Vref and GND		1		nF
R <sub>FLAG_F</sub>	The pull-up resistence is connected between FLAG_F and VCC		10		kΩ
R <sub>FLAG_S</sub>	The pull-up resistence is connected between FLAG_S and VCC		10		kΩ



# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

# **Common Electrical Characteristics**

Characteristic	Symbol	Test Conditions	Min	Тур	Max	Unit
C	V	Operating, SC8450XXX-XXX3	3	3.3	3.6	V
Supply Voltage	$V_{CC}$	Operating, SC8460XXX-XXX5	4.5	5.0	5.5	V
Sl Ct	т	$V_{CC} = 4.5 \sim 5.5 \text{ V}$ , output open		22		mA
Supply Current	$I_{CC}$	$V_{CC} = 3 \sim 3.6 \text{V}$ , output open		15		mA
Output Resistive Load	$R_{\rm L}$	Between VIOUT and GND	2			kΩ
VREF Resistive Load	R <sub>LREF</sub>	Between VREF and GND	2			kΩ
Anti-external magnetic interference suppression ratio	CMFR	The external interference magnetic field perpendicular to the chip surface		-36		dB
Primary Conductor Resistance	R <sub>PRIMARY</sub>	$T_A = 25$ °C		0.24		mΩ
Temperature Coefficient of Primary Conductor Resistance	$TC_R$	T <sub>A</sub> =-40~125°C		3421		ppm/°C
Hysteresis Voltage	V <sub>hys</sub>	Viout(IP to +40A then return to 0A)- Viout(IP to -40A,then return to 0A)		1		mV
Rise time	$t_r$	IP=50A/uS		2.08		uS
Propagation Delay	$t_{pd}$	IP=50A/uS		1.15		uS
Response Time	tresponse	IP=50A/uS		1.82	2	μS
Bandwidth	f	Small-signal −3 dB,		240		kHz
		BW=240KHz		38.7		mA(rms)
Noise	$I_N$	BW=10KHz		6		mA(rms)
		BW=1KHz		2		mA(rms)
Nonlinearity	$E_{LIN}$	-100A <ip<100a< td=""><td></td><td></td><td>1</td><td>%</td></ip<100a<>			1	%
Bidirectional Quiescent Output(suitable for product with suffix B3)	$S_{\mathrm{coef}}$	VCC=3.3V, S <sub>coef</sub> =Sens(VCC)/Sens(3.3V)		VCC/3.3		
Bidirectional Quiescent Output(suitable for product with suffix B5)	Scoef_B5	VCC=5.0V, Scoof=Sens(VCC)/Sens(5V)		VCC/5		
VIOUT Linear Rail to Rail Output Range	Vrail-rail	$R_L=4.7k\Omega$	10		90	%VCC
Power-On Time	$t_{PO}$	Output reaches steady state level, $T_J = 25^{\circ}C$		150		μS



#### Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### FLAG overcurrent detection of electrical parameters

Note1: Over full range of TA=25°C,  $C_{Bypass}$ =0.47uF,  $C_{Load}$ =1.0nF,  $R_{pu}$ =10k $\Omega$ ,  $V_{CC}$ =3.3/5V

Note 2: Whether FLAG S or FLAG F sets the trigger threshold current, it is recommended that the actual loaded effective current is 1.15\*IFLAG

Characteristic Characteristic	Symbol	Test Conditions	Min	Тур	Max	Unit			
Overcurrent detection of electrical parameters									
OC_SET external input range	Voc_set	OC_SET input voltage	0		Vcc	V			
OC_SET PIN input current	$I_{IN}$	High impedance, pin input current			8	uA			
Fault output low voltage	$V_{FLAG}$	$R_{PU}=10k\Omega$	0		0.5	V			
FLAG_F built-in fault range	$I_{FLAG\ (F)}$	Supported built-in multiples ( $I_{PR}$ =peak current) , See the corresponding model Settings for details		0.75*IPR~2 *IPR		A			
		$OC\_SET \in (0.3*Vcc, 0.34*Vcc)$		IPR*0.75		A			
		$OC\_SET \in (0.41*Vcc, 0.45*Vcc)$		IPR*1		A			
FLAG_S adjustable fault	T	$OC\_SET \in (0.55*Vcc, 0.59*Vcc)$		IPR*1.25		A			
range [1]	$I_{FLAG\ (S)}$	$OC\_SET \in (0.65*Vcc, 0.71*Vcc)$		IPR*1.5		A			
		$OC\_SET \in (0.79*Vcc, 0.83*Vcc)$		IPR*1.75		A			
		$OC\_SET \in (0.91*Vcc, 0.97*Vcc)$		IPR*2		A			
FLAG_F restore the threshold point [2]	Ire	Current drops to IRE until VFLAG returns to high level		50%*I <sub>FLAG</sub>		A			
FLAG_S restore the threshold point [2]	IRE			50%*I <sub>FLAG</sub>		A			
FLAG_F back difference value	$I_{\mathrm{HYS}}$			50%*I <sub>FLAG</sub>		A			
FLAG_F back difference value	IHYS	Ihys=  Iflag-Ire		50%*I <sub>FLAG</sub>		A			
	Dy	namic response characteristics of overcurrent of	letection	, ,		T			
fault clearance time	$T_{CF}$	The time from the IP address falling below IFLAG-IHYs to the time when VFLAG is pulled above VFLAG; $R_{PU}$ =10 $k\Omega$		3		uS			
FLAG output response time [3]	$T_R$	$R_{PU}$ =10k $\Omega$ When the current step jumps to IFLAG*1.15, the response time between FLAG < VFLAG		1.5	2	uS			
FLAG_F output hold time [4]	Thold (FLAG_F)	FLAG_F output continues to pull down time		10		uS			
Extra duration of current [4]	$T_{MASK} \\ (FLAG\_S)$	There must be time to determine the fault and reduce interference and false triggering		3		uS			
FLAG_S output hold time [4]	Thold (FLAG_S)	FLAG_S output continues to pull down time		10		uS			

<sup>[1]</sup> The relationship between the threshold setting of FLAG\_S and the overcurrent trigger point is set in STEP mode to prevent false trigger. The overcurrent trigger point is determined by the voltage obtained by OC\_SET, not the resistance value, as described in the section "OC\_SET Pin Relationship with FLAG\_S".

<sup>[2]</sup> If the absolute value of the IP is higher than IFLAG (S) or IFLAG (F), the internal fault comparator will trip. The IP must be lower than the IRE before the internal fault comparator will reset.

<sup>[3]</sup> Response time: It is recommended to obtain the response time <1.5uS when the actual loading current is IFLAG\*1.15

<sup>[4]</sup> In order to ignore the false triggering of the interference current pulse in the application, the FLAG\_S trigger condition requires that the primary input current should remain 3uS after the Tr time, which can be simply understood as the total duration of the primary current: Tr+TMASK

<sup>[4]</sup> Factory shipment defaultMask=0uS, The function is disabled

<sup>[2/3/4]</sup> Design guarantee



# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8450A1FT-100B3 Individual Performance Characteristics

Parameter	Symbol	Test Conditions	Min	$Typ^{[1]}$	Max	Unit				
	NOMINAL PERFORMANCE (Regardless of life time drift error )									
Current-Sensing Range	$I_{PR}$		-100		100	A				
IP=0A, VIOUT output	$V_{ m OQ}$	IP=0A		0.5Vcc		V				
voltage	VOQ			0.5 v cc						
VREF output voltage	Vref	Independent of the IP input current		$0.5V_{CC}$		V				
Sensitivity	Sens	-100A <ip<100a< td=""><td></td><td>13.2</td><td></td><td>mV/A</td></ip<100a<>		13.2		mV/A				
Built-in flow threshold range	$FLAG_{\left( IF\right) }$	Built-in overcurrent threshold (Built-in 10)		125		A				
Low speed overflow threshold range [2]	FLAG (IS)	Min=I <sub>PR</sub> *0.75, Max= I <sub>PR</sub> *2	75		200	A				
		ACCURACY PERFORMANCE								
		$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%				
Sensitivity Error	Esens	$I_{PR} = \pm 100 \text{ A}, T_A = 25 \sim 125 ^{\circ}\text{C}$		±2.5		%				
·		$I_{PR} = \pm 100 \text{ A}, T_A = -40 \sim 25^{\circ}\text{C}$		±2.5		%				
	Evoq	$I_P=0A, T_A=25^{\circ}C$		±12		mV				
Single output zero error		$I_P=0A$ , $T_A = 25 \sim 125$ °C		±15		mV				
		$I_P=0A$ , $T_A = -40\sim25$ °C		±15		mV				
Differential Output zero		$I_P=0A, T_A=25$ °C		±10		mV				
Error	Evoe	$I_P=0A$ , $T_A=25\sim125$ °C		±15		mV				
		$I_P=0A, T_A=-40\sim25^{\circ}C$		±15		mV				
TOTAL	OUTPUT ERRO	$R COMPONENTS : E_{TOT} = \{[V_{IOUT}\_ideal(I_{PR})\}\}$	V <sub>IOUT</sub> (I <sub>PR</sub> )]/[	Sens <sub>idea</sub> l*I <sub>PR</sub> ]}	*100%					
		$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%				
Total Output Error	$E_{TOT}$	$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ}\text{C} \sim 125^{\circ}\text{C}$		±2		%				
		$I_{PR} = \pm 100 \text{ A}, T_A = -40 \text{°C} \sim 25 \text{°C}$		±3		%				
		Accuracy of overcurrent fault threshol	d							
Built-in fault output	E <sub>IFLAG_F</sub>	$T_A=25$ °C		±15		%				
Dulit-in fault output	□IFLAG_F	T <sub>A</sub> = -40°C~125°C		±25		%				
Adjustable fault output	E <sub>IFLAG_S</sub>	I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%				
Adjustable fault output		I <sub>PR</sub> *2, T <sub>A</sub> =-40°C~125°C		±25	, ,	%				

<sup>[1]</sup> The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

<sup>[2]</sup> For details about the relationship between the IFLAG\_S overcurrent trigger threshold and OC\_SET, see "The Relationship between OC\_SET Pins and FLAG\_S".



# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8450A1FT-150B3 Individual Performance Characteristics

Parameter	Symbol	Test Conditions	Min	$\mathbf{Typ}^{[1]}$	Max	Unit			
	NOMINAL PERFORMANCE (Regardless of life time drift error )								
Current-Sensing Range	$I_{PR}$		-150		150	A			
IP=0A, VIOUT output	Voo	IP=0A		0.5Vcc		V			
voltage		IF-0A		0.5 v cc					
VREF output voltage	Vref	Independent of the IP input current		$0.5V_{CC}$		V			
Sensitivity	Sens	-150A <ip<150a< td=""><td></td><td>8.8</td><td></td><td>mV/A</td></ip<150a<>		8.8		mV/A			
Built-in flow threshold range	FLAG <sub>(IF)</sub>	Built-in overcurrent threshold (Built-in 10)		187.5		A			
Low speed overflow threshold range [2]	FLAG (IS)	Min=I <sub>PR</sub> *0.75, Max= I <sub>PR</sub> *2	112.5		300	A			
threshold range		ACCURACY PERFORMANCE							
		$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%			
Sensitivity Error	Esens			±1.3		%			
Sensitivity Error	LSENS	$I_{PR} = \pm 150 \text{ A}, T_A = 25 \sim 125 ^{\circ}\text{C}$ $I_{PR} = \pm 150 \text{ A}, T_A = -40 \sim 25 ^{\circ}\text{C}$		+2.5		%			
		$I_{P} = 0A, T_{A} = 25^{\circ}C$		+10		mV			
Single output zero error	Evoq	$I_P=0A$ , $I_A=25$ °C $I_P=0A$ , $T_A=25$ °C		±15		mV			
Single output zero error		$I_{P}=0A$ , $I_{A}=-40\sim25$ °C		±15		mV			
		$I_{P}=0A$ , $T_{A}=25^{\circ}C$		±10		mV			
Differential Output zero	Evoe	$I_P=0A$ , $T_A=25\sim125$ °C		±15		mV			
Error		$I_P=0A, T_A=-40\sim25^{\circ}C$		±15		mV			
TOTAL	OUTPUT ERRO	R COMPONENTS : ETOT = {[VIOUT_ideal(IPR)	-V <sub>IOUT</sub> (I <sub>PR</sub> )]/	[Sens <sub>idea</sub> l*I <sub>PR</sub> ]	}*100%				
		$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ}\text{C}$		±2		%			
Total Output Error	$E_{TOT}$	$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ}\text{C} \sim 125^{\circ}\text{C}$		±2		%			
		$I_{PR} = \pm 150 \text{ A}, T_A = -40^{\circ}\text{C} \sim 25^{\circ}\text{C}$		±3		%			
		Accuracy of overcurrent fault threshol	d						
Built-in fault output	E <sub>IFLAG_F</sub>	$T_A=25$ °C		±15		%			
Bunt-in faun output	L'IFLAG_F	T <sub>A</sub> = -40°C~125°C		±25		%			
Adjustable fault output	Eiflag_s	I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%			
Adjustable fault output		I <sub>PR</sub> *2, T <sub>A</sub> =-40°C~125°C		±25		%			

<sup>[1]</sup> The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

<sup>[2]</sup> For details about the relationship between the IFLAG\_S overcurrent trigger threshold and OC\_SET, see "The Relationship between OC\_SET Pins and FLAG\_S".



# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8450A1FT-50F3 Individual Performance Characteristics

Parameter	Symbol	Test Conditions	Min	$\mathbf{Typ}^{[1]}$	Max	Unit			
	NOMINAL PERFORMANCE (Regardless of life time drift error )								
Current-Sensing Range	$I_{PR}$		-50		50	A			
IP=0A, VIOUT output	Voo	IP=0A		1.65		V			
voltage		IF-0A		1.05					
VREF output voltage	Vref	Independent of the IP input current		1.65		V			
Sensitivity	Sens	-50A <ip<50a< td=""><td></td><td>26.4</td><td></td><td>mV/A</td></ip<50a<>		26.4		mV/A			
Built-in flow threshold range	FLAG <sub>(IF)</sub>	Built-in overcurrent threshold (Built-in 10)		62.5		A			
Low speed overflow threshold range [2]	FLAG (IS)	Min=I <sub>PR</sub> *0.75, Max= I <sub>PR</sub> *2	37.5		100	A			
threshold range		ACCURACY PERFORMANCE		1					
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%			
Sensitivity Error	Esens	$I_{PR} = \pm 50 \text{ A}, T_A = 25 \sim 125 \text{ °C}$		±2		%			
		$I_{PR} = \pm 50 \text{ A}, T_A = -40 \sim 25 \text{ °C}$		±2.5		%			
		$I_{P}=0A, T_{A}=25^{\circ}C$		±10		mV			
Single output zero error	Evoq	$I_P=0A, T_A=25\sim125$ °C		±15		mV			
		$I_P=0A$ , $T_A = -40\sim25$ °C		±15		mV			
Differential Output zero		$I_P=0A, T_A=25$ °C		±10		mV			
Error	Evoe	$I_P=0A$ , $T_A = 25 \sim 125$ °C		±15		mV			
		$I_P=0A, T_A=-40\sim25^{\circ}C$		±15		mV			
TOTAL	OUTPUT ERRO	$R COMPONENTS : E_{TOT} = \{[V_{IOUT}\_ideal(I_{PR})]\}$	-V <sub>IOUT</sub> (I <sub>PR</sub> )]/	[Sens <sub>idea</sub> l*I <sub>PR</sub> ]	}*100%				
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C}$		±2		%			
Total Output Error	$E_{TOT}$	$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C} \sim 125^{\circ}\text{C}$		±2		%			
		$I_{PR} = \pm 50 \text{ A}, T_A = -40 \text{°C} \sim 25 \text{°C}$		±3		%			
		Accuracy of overcurrent fault threshol	d						
Built-in fault output	E <sub>IFLAG_F</sub>	$T_A=25$ °C		±15		%			
Dulit-in fault output	□IFLAG_F	T <sub>A</sub> = -40°C~125°C		±25		%			
Adjustable fault output	E <sub>IFLAG_S</sub>	I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%			
Adjustable fault output		I <sub>PR</sub> *2, T <sub>A</sub> =-40°C~125°C	,	±25		%			

<sup>[1]</sup> The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

<sup>[2]</sup> For details about the relationship between the IFLAG\_S overcurrent trigger threshold and OC\_SET, see "The Relationship between OC\_SET Pins and FLAG\_S".



# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

# SC8460A1FT-50F5 Individual Performance Characteristics

Parameter	Symbol	Test Conditions	Min	$\mathbf{Typ}^{[1]}$	Max	Unit		
NOMINAL PERFORMANCE (Regardless of life time drift error )								
Current-Sensing Range	$I_{PR}$		-50		50	Α		
IP=0A, VIOUT output	$V_{\mathrm{OQ}}$	IP=0A		2.5		V		
voltage	¥0Q	II -0A		2.3				
VREF output voltage	Vref	Independent of the IP input current		2.5		V		
Sensitivity	Sens	-50A <ip<50a< td=""><td></td><td>40</td><td></td><td>mV/A</td></ip<50a<>		40		mV/A		
Built-in flow threshold	$FLAG_{(IF)}$	Built-in overcurrent threshold (Built-in 10)		62.5		A		
range								
Low speed overflow	FLAG (IS)	$Min=I_{PR} *0.75$ , $Max=I_{PR} *2$	37.5		100	A		
threshold range [2]								
		ACCURACY PERFORMANCE	1	I	ı	1		
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%		
Sensitivity Error	Esens	$I_{PR} = \pm 50 \text{ A}, T_A = 25 \sim 125 \text{ °C}$		±2		%		
		$I_{PR} = \pm 50 \text{ A}, T_A = -40 \sim 25 \text{ °C}$		±2.5		%		
	Evoq	$I_P=0A, T_A=25^{\circ}C$		±10		mV		
Single output zero error		$I_P=0A$ , $T_A = 25 \sim 125$ °C		±15		mV		
		$I_P=0A, T_A=-40\sim25^{\circ}C$		±15		mV		
Differential Output zero		$I_P=0A, T_A=25^{\circ}C$		±10		mV		
Error	Evoe	$I_P=0A$ , $T_A = 25 \sim 125$ °C		±15		mV		
		$I_P=0A$ , $T_A = -40\sim25$ °C		±15		mV		
TOTAL	OUTPUT ERRO	$R COMPONENTS : E_{TOT} = \{[V_{IOUT}\_ideal(I_{PR})]\}$	-VIOUT(IPR)]/[	Sensideal*IPR]	}*100%			
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C}$		±2		%		
Total Output Error	$E_{TOT}$	$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C} \sim 125^{\circ}\text{C}$		±2		%		
_		$I_{PR} = \pm 50 \text{ A}, T_{A} = -40 \text{°C} \sim 25 \text{°C}$		±3		%		
Accuracy of overcurrent fault threshold								
Built-in fault output	E	$T_A=25$ °C		±15		%		
	$\mathrm{E}_{\mathrm{IFLAG\_F}}$	T <sub>A</sub> = -40°C~125°C		±25		%		
A disastable facile automot	E	I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%		
Adjustable fault output	E <sub>IFLAG_S</sub>	I <sub>PR</sub> *2, T <sub>A</sub> =-40°C~125°C		±25		%		

<sup>[1]</sup> The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

<sup>[2]</sup> For details about the relationship between the IFLAG\_S overcurrent trigger threshold and OC\_SET, see "The Relationship between OC\_SET Pins and FLAG\_S".



# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8460A1FT-50B5 Individual Performance Characteristics

Parameter	Symbol	Test Conditions	Min	$\mathbf{Typ}^{[1]}$	Max	Unit		
NOMINAL PERFORMANCE (Regardless of life time drift error )								
Current-Sensing Range	$I_{PR}$		-50		50	A		
IP=0A, VIOUT output	Voo	IP=0A		0.5Vcc		V		
voltage				0.5 VCC				
VREF output voltage	Vref	Independent of the IP input current		0.5Vcc		V		
Sensitivity	Sens	-50A <ip<50a< td=""><td></td><td>40</td><td></td><td>mV/A</td></ip<50a<>		40		mV/A		
Built-in flow threshold range	FLAG <sub>(IF)</sub>	Built-in overcurrent threshold (Built-in 10)		62.5		A		
Low speed overflow threshold range [2]	FLAG (IS)	Min=I <sub>PR</sub> *0.75, Max= I <sub>PR</sub> *2	37.5		100	A		
and control of the co		ACCURACY PERFORMANCE						
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%		
Sensitivity Error	Esens	$I_{PR} = \pm 50 \text{ A}, T_A = 25 \sim 125 \text{ °C}$		±2		%		
-		$I_{PR} = \pm 50 \text{ A}, T_A = -40 \sim 25 \text{ °C}$		±2.5		%		
		$I_P=0A, T_A=25^{\circ}C$		±10		mV		
Single output zero error	Evoq	$I_P=0A$ , $T_A = 25 \sim 125$ °C		±15		mV		
		$I_P=0A$ , $T_A = -40\sim25$ °C		±15		mV		
Differential Output zero		$I_P=0A, T_A=25$ °C		±10		mV		
Error	Evoe	$I_P=0A$ , $T_A = 25 \sim 125$ °C		±15		mV		
		$I_P=0A, T_A=-40\sim25^{\circ}C$		±15		mV		
TOTAL	OUTPUT ERRO	$R COMPONENTS : E_{TOT} = \{[V_{IOUT}\_ideal(I_{PR})]\}$	-V <sub>IOUT</sub> (I <sub>PR</sub> )]/	[Sens <sub>idea</sub> l*I <sub>PR</sub> ]	<b>}*100%</b>			
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C}$		±2		%		
Total Output Error	$E_{TOT}$	$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C} \sim 125^{\circ}\text{C}$		<u>+2</u>		%		
		$I_{PR} = \pm 50 \text{ A}, T_A = -40^{\circ}\text{C} \sim 25^{\circ}\text{C}$		±3		%		
Accuracy of overcurrent fault threshold								
Built-in fault output	E <sub>IFLAG_F</sub>	$T_A=25$ °C		±15		%		
Dant in fault output	₽IFLAU_F	T <sub>A</sub> = -40°C~125°C		±25		%		
Adjustable fault output	E <sub>IFLAG_S</sub>	I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%		
Adjustable fault output		I <sub>PR</sub> *2, T <sub>A</sub> =-40°C~125°C	,	±25		%		

<sup>[1]</sup> The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

<sup>[2]</sup> For details about the relationship between the IFLAG\_S overcurrent trigger threshold and OC\_SET, see "The Relationship between OC\_SET Pins and FLAG\_S".



# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8460A1FT-100B5 Individual Performance Characteristics

Parameter	Symbol	Test Conditions	Min	$\mathbf{Typ}^{[1]}$	Max	Unit		
NOMINAL PERFORMANCE (Regardless of life time drift error )								
Current-Sensing Range	$I_{PR}$		-100		100	Α		
IP=0A, VIOUT output	$V_{\mathrm{OQ}}$	IP=0A		0.5Vcc		V		
voltage	VOQ			0.5 v cc				
VREF output voltage	Vref	Independent of the IP input current		0.5V <sub>CC</sub>		V		
Sensitivity	Sens	-100A <ip<100a< td=""><td></td><td>20</td><td></td><td>mV/A</td></ip<100a<>		20		mV/A		
Built-in flow threshold range	FLAG(I <sub>F)</sub>	Built-in overcurrent threshold (Built-in 10)		125		A		
Low speed overflow threshold range [2]	FLAG (Is)	Min=I <sub>PR</sub> *0.75, Max= I <sub>PR</sub> *2	75		200	A		
		ACCURACY PERFORMANCE						
		$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%		
Sensitivity Error	Esens	$I_{PR} = \pm 100 \text{ A}, T_A = 25 \sim 125 \text{ °C}$		±2		%		
		$I_{PR} = \pm 100 \text{ A}, T_A = -40 \sim 25 ^{\circ}\text{C}$		±2.5		%		
	Evoq	$I_P=0A, T_A=25$ °C		±12		mV		
Single output zero error		$I_P=0A$ , $T_A = 25 \sim 125$ °C		±15		mV		
		$I_P=0A, T_A=-40\sim25^{\circ}C$		±15		mV		
Differential Output zero	Evoe	$I_P=0A, T_A=25^{\circ}C$		±10		mV		
Error		$I_P=0A$ , $T_A = 25 \sim 125$ °C		±15		mV		
		$I_P=0A, T_A=-40\sim25^{\circ}C$		±15		mV		
TOTA	L OUTPUT ERRO	OR COMPONENTS: $E_{TOT} = \{[V_{IOUT}\_ideal(I_{PR})]\}$	-Viout(Ipr)]/	[Sens <sub>idea</sub> l*I <sub>PR</sub> ]	]}*100%			
		$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%		
Total Output Error	$E_{TOT}$	$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ}\text{C} \sim 125^{\circ}\text{C}$		±2		%		
		$I_{PR} = \pm 100 \text{ A}, T_{A} = -40 \text{ °C} \sim 25 \text{ °C}$		±3		%		
Accuracy of overcurrent fault threshold								
Built-in fault output	Everyone	$T_A=25$ °C		±15		%		
Bunt-in faunt output	E <sub>IFLAG_F</sub>	T <sub>A</sub> = -40°C~125°C		±25		%		
A divistable foult output	Ever e a a	I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%		
Adjustable fault output	E <sub>IFLAG</sub> _S	I <sub>PR</sub> *2, T <sub>A</sub> =-40°C~125°C		±25		%		

<sup>[1]</sup> The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

<sup>[2]</sup> For details about the relationship between the IFLAG\_S overcurrent trigger threshold and OC\_SET, see "The Relationship between OC\_SET Pins and FLAG\_S".



# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8460A1FT-150B5 Individual Performance Characteristics

参数名称	参数符号	测试条件	最小值	典型值1	最大值	单位		
NOMINAL PERFORMANCE (Regardless of life time drift error )								
Current-Sensing Range	$I_{PR}$		-150		150	A		
IP=0A, VIOUT output	$V_{ m OQ}$	IP=0A		0.5Vcc		V		
voltage	VOQ	IF-0A		0.5 VCC				
VREF output voltage	Vref	Independent of the IP input current		$0.5 V_{CC}$		V		
Sensitivity	Sens	-150A <ip<150a< td=""><td></td><td>13.33</td><td></td><td>mV/A</td></ip<150a<>		13.33		mV/A		
Built-in flow threshold range	FLAG(I <sub>F)</sub>	Built-in overcurrent threshold (Built-in 10)		187.5		A		
Low speed overflow	FLAG (Is)	Min=I <sub>PR</sub> *0.75, Max= I <sub>PR</sub> *2	112.5		300	A		
threshold range [2]								
_		ACCURACY PERFORMANCE						
		$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%		
Sensitivity Error	Esens	$I_{PR} = \pm 150 \text{ A}, T_A = 25 \sim 125 ^{\circ}\text{C}$		±2		%		
		$I_{PR} = \pm 150 \text{ A}, T_A = -40 \sim 25^{\circ}\text{C}$		±2.5		%		
	Evoq	$I_P=0A, T_A=25^{\circ}C$		±10		mV		
Single output zero error		$I_P=0A$ , $T_A=25\sim125$ °C		±15		mV		
		$I_P=0A$ , $T_A = -40\sim25$ °C		±15		mV		
Differential Output zero	Evoe	$I_P=0A, T_A=25$ °C		±10		mV		
Error		$I_P=0A$ , $T_A=25\sim125$ °C		±15		mV		
-		$I_P=0A, T_A=-40\sim25^{\circ}C$		±15		mV		
TOTAL	OUTPUT ERRO	R COMPONENTS: $E_{TOT} = \{[V_{IOUT}\_ideal(I_{PR})\}\}$	VIOUT(IPR)]/[S		*100%	1		
		$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ}\text{C}$		±2		%		
Total Output Error	$E_{TOT}$	$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ}\text{C} \sim 125^{\circ}\text{C}$		±2		%		
		$I_{PR} = \pm 150 \text{ A}, T_A = -40^{\circ}\text{C} \sim 25^{\circ}\text{C}$		±3		%		
Accuracy of overcurrent fault threshold								
Built-in fault output	Eiflag f	$T_A=25$ °C		±15		%		
	LIFLAU_F	T <sub>A</sub> = -40°C~125°C		±25		%		
Adjustable fault output	E <sub>IFLAG_S</sub>	I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%		
Aujustable fault bulput	LIFLAG_S	I <sub>PR</sub> *2, T <sub>A</sub> =-40°C~125°C		±25		%		

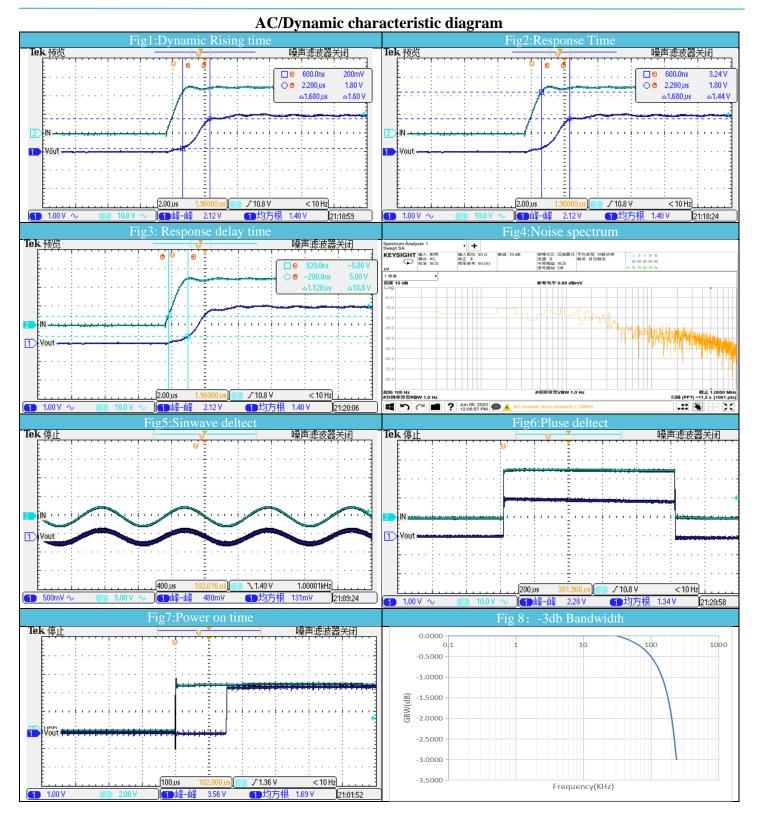
<sup>[1]</sup> The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

<sup>[2]</sup> For details about the relationship between the IFLAG\_S overcurrent trigger threshold and OC\_SET, see "The Relationship between OC\_SET Pins and FLAG\_S".



Accuracy Characteristic Curve (SC8450A1FT-100B3) Fig2; Offset Voltage vs. Temp 20.0 20.0 Offset Voltage(mV) Offset Voltage(mV) 15.0 10.0 10.0 5.0 0.0 0.0 105 125 25 50 125 -5.0 -10.0 -10.0 -20.0 -15.0 3sigma -3sigma -3sigma -3sigma average average Fig3:Sensitivity Error vs. Temp 3.00% 13.50 13.40 Sensitivity Error(%) 2.00% 13.30 1.00% 13.20 0.00% 13.10 105 13.00 -1.00% 12.90 -2.00% 12.80 3sigma -3sigma -40 -20 105 125 Fig5:Linearity error vs. Primary current Fig6:Toltal output Error vs Linearity error (%) 4.00% 0.1500 3.00% Total Error(%) 0.1000 2.00% Linearity error - £L [%] 0.0500 1.00% 0.00% 0.0000 -1.00% -0.0500 -2.00% -0.10003sigma -3sigma -average -0.1500 Primary current (A) Fig7:FLAG\_F error vs. Temp Fig8:FLAG\_S error vs. Temp 20.00% 0.00% -40 -20 25 50 85 105 125 15.00% FLAG\_S Error(%) -0.50% FLAG\_F Error(%) 10.00% 5.00% -1.00% 0.00% -40 -20 0 25 125 -1.50% -5.00% -10.00% -2.00% -0.25IP -0.75IP







# **Functional Description**

# **◆** Internal Reference Voltage

Vref is always equal to the static bias output value of VIOUT, that is, VIOUT value when IP=0A.

The relationship between VIOUT and Vref obey that following formula:

VIOUT=IP\*Sens+Vref,

When SC84xxAFT\*\*Fx is used, VREF constantly outputs 2.5V/1.65V, And has a driving capacity of more than 30mA;

When SC84xxAFT\*\*Bx is used, VREF constantly outputs 0.5VCC, And has a driving capacity of more than 30mA;

#### **◆** Overcurrent Function

#### Description:

With two overcurrent fault comparators:

- FLAG\_F: When FLAG\_F pins are pulled up, the default output is high. When the absolute value of the input current exceeds IPR\* multiple, the comparator tripping output is pulled down to low level. This function has a <2uS ultra-fast response time, which is very suitable for detection and verification of short circuit events. The overcurrent must be maintained at least 1uS in order to be detected, and after the detection of the post stage, the output low signal will maintain a residence time of 10uS, so that the controller can easily detect the overcurrent signal.
- FLAG\_S: After FLAG\_S pin is pulled up, the default output is high. When the absolute value of the input current exceeds the set threshold, the comparator tripping output is pulled down to the low level. This function improves the high precision characteristic and is suitable for the detection of overload conditions beyond the range. The overcurrent must be maintained at least 3uS in order to be detected, and after the detection of the post stage, the output low signal will maintain a residence time of 10uS, so that the controller can easily detect the overcurrent signal.

OC\_SET: Allows users to set the FLAG\_S trip threshold through external voltage dividers. The relationship between OC\_SET pins and FLAG\_S is shown in the following table:

# OC\_SET PIN and FLAG\_S Relationship

OC_SET input voltage [1]	IFLAG_S trigger threshold [2]		
VCC= 3.3V and 5V	SC8450Axxx-xxBx SC8460Axxx-xxBx		
OC_SET ∈ (0.3*Vcc, 0.34*Vcc)	IPR*0.75		A
OC_SET ∈ (0.41*Vcc, 0.45*Vcc)	IPR*1		A
OC_SET ∈ (0.55*Vcc, 0.59*Vcc)	IPR*1.25		A
OC_SET ∈ (0.65*Vcc, 0.71*Vcc)	IPR*1.5		A
OC_SET ∈ (0.79*Vcc, 0.83*Vcc)	$ET \in (0.79*Vcc, 0.83*Vcc)$ IPR*1.75		A
$OC\_SET \in (0.91*Vcc, 0.97*Vcc)$ IPR*2		2	A



#### [1] OC SET function:

- 1) OC\_SET input voltage supports 0.3\*VCC~0.97\*VCC range, users can set the overcurrent alarm threshold of FLAG\_S pin through the OC\_SET input voltage (as shown in the above table), the input voltage is allowed to use VCC and resistance partial voltage for adaptive (Figure 1). When the OC\_SET input voltage is in the range of OC\_SET ∈ (0.3\*VCC, 0.34\*VCC), it corresponds to the minimum trigger point IFLAG; when the OC\_SET input voltage is in the range of OC\_SET ∈ (0.91\*VCC, 0.97\*VCC), it corresponds to the maximum trigger point IFLAG.
- 2) OC\_SET input voltage supports 0.3\*VCC~0.97\*VCC range, but it should be noted that it is not a linear selection, but designed into a STEP mode, set into 6 intervals, each interval has an input voltage range to correspond to the IFLAG overcurrent trigger threshold.

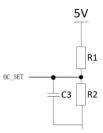


Figure 1: OC SET resistor divider

#### [2] IFLAG trigger threshold:

Whether FLAG\_S or FLAG\_F sets the trigger threshold current, it is recommended that the actual loaded effective current is IFLAG\* 1.15

#### FLAG output characteristic diagram:

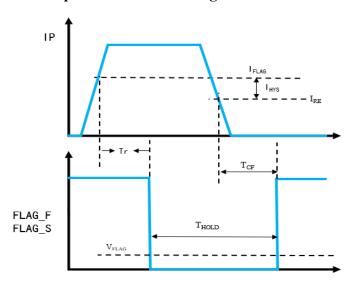


Figure 2: Fault response timing when the Tmask function is disabled

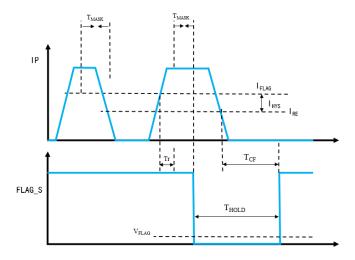


Figure 3: FLAG S timing diagram when Tmsk function is enabled

# Figure 2 The fault feature applies to FLAG\_F as well as to FLAG\_S, which is disabled by Tmask

When the current through the IP exceeds the IFLAG threshold, after the Tr delay time, the FLAG\_F fault pin will trip, and the fault will remain active for a period of time until the absolute current is less than the fault threshold (IRE).

# Figure 3 Fault characteristics apply to FLAG S when the Tmask function is enabled

TMASK is defined as the extra time that the primary side current must be present after the Tr time has passed.

As shown in Figure 3, where the width of the first current transient pulse is smaller than TMASK, the purpose is that if a fault occurs, but the fault duration is smaller than TMASK, the device will not report the fault, which can prevent the wrong alarm caused by the interference signal of the transient current pulse.

When the second current pulse exceeds the IFLAG threshold and after a time of ≥TMASK, the fault is triggered and the output is pulled down, until the absolute current is less than the fault threshold (IRE), the fault will remain active for a period of time until the fault state is over and reset.



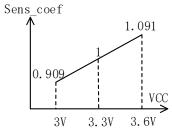
#### **♦** Proportional Coefficient Of Sensitivity

Sensitivity ratio coefficient (sens\_coef), which defines the coefficient proportional to the sensitivity and VCC. The ideal coefficient is 1. If the VCC increases by 10%, the sensitivity will increase by 10%. At this time, the coefficient is 1.1, which means that the sensitivity increases by 10% compared with the ideal proportion. The relationship between the scale coefficient is described by the following equation:

Scoef=Sens coef=SENS<sub>VCC</sub>/SENS<sub>VCCN</sub>

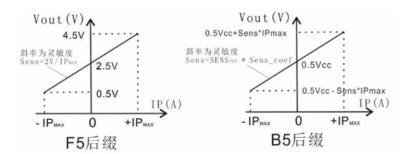
It is the ratio of the sensitivity SENSVCC under the supply voltage Vcc to the sensitivity SENSVCCN under the rated supply voltage VCCN. Through this value, we can get the sensitivity under any supply voltage.

In ideal situation:



# **♦** Proportional Relationship

Using SC8450\_60\*\*B\*, sensitivity and zero voltage are changing with VCC proportion, zero for the VCC / 2, sensitivity to SENS<sub>VCC</sub>\* Sens\_coef. Using SC8450\_60\*\*F\*, sensitivity and zero voltage are changing with VCC proportion, zero for the 0.1VCC, sensitivity to SENS<sub>VCC</sub>\* Sens\_coef.



#### **◆** Impact of External Magnetic Fields

CMFR is used to express the ability of sensor resisting impact of external magnetic fields. The larger the absolute value of CMFR, the stronger the ability to resist external magnetic interference is.

$$CMFR = 20 \lg \left| \frac{A_{CM}}{Sens/CF} \right|$$

Where CF is the magnetic field coupling factor of the primary current in the sensor, Sens is the sensor sensitivity, and Sens/CF represents the change ratio of the sensor itself in mv/G.

For example: CMFR= -40dB, Sens = 40mv/A, CF = 10G/A, then ACM is 0.04mv/G.

#### **♦** Delay time t<sub>pd</sub> and Response time t<sub>response</sub>

Both delay time and response time are used to characterize the time difference between primary side and secondary side;

The delay time is the time difference when the secondary output reaches 20% of the steady-state output value and the primary output reaches 20% of the steady-state current;

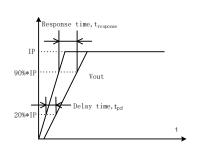
The response time is the time difference when the secondary output reaches 90% of the steady-state output value and the primary output reaches 90% of the steady-state current.

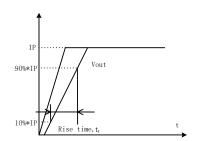
#### Rise Time t<sub>r</sub>

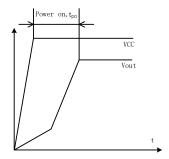
The rising time is used to represent the time difference of the secondary side itself, that is, the time difference between the time when the output of the secondary side reaches 90% of the steady-state output value and 10% of the steady-state output value.

#### Power-On Time tpo

Power-On Time is defined as the time it takes for the output voltage to settle within  $\pm 10\%$  of its steady-state value under an applied magnetic field, after the power supply has reached its minimum specified operating voltage.







#### ♦ Thermal resistance R<sub>θJA</sub>

Based on a demo board, the thermal resistance is calculated by measuring the chip top temperature and power value. According to the thermal resistance, the junction temperature can be calculated as a reference. The actual surface temperature measurement value is shown in the relationship between the package temperature and the measured current.

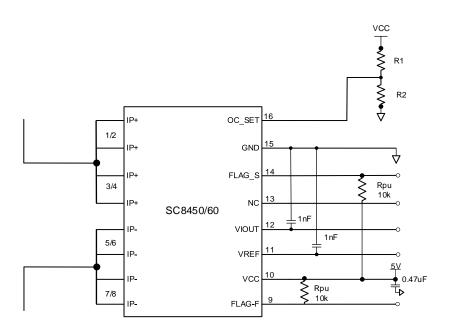
$$T_{J} = T_{A} + \left(R_{\theta JA} * POWER\right) = T_{A} + \left(R_{\theta JA} * IP^{2} * R_{PRIMARY}\right);$$

Where T<sub>J</sub> is junction temperature and T<sub>A</sub> is ambient temperature.



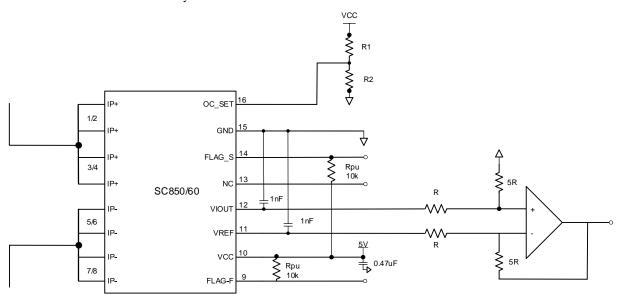
# **♦** Reference application circuit diagram

1. Schematic diagram of connection between SC8450/60 and overcurrent detection



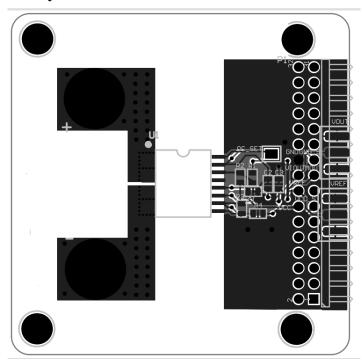
2. SC8450/60 VOUT and VREF Differential application diagram:

As below: VIOUT = IP \* Sensitivity \* (5R/R)

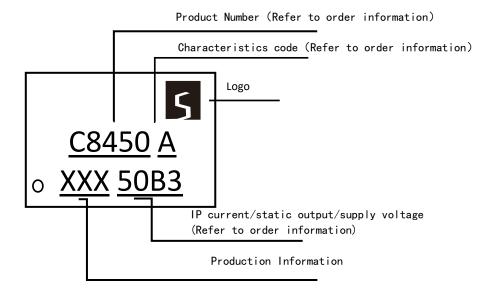




#### **PCB Demo Evaluation Board Layout**



# **Mark Description**

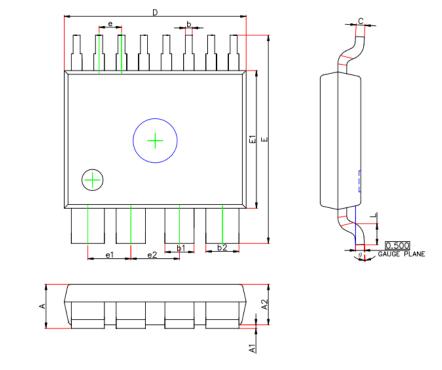


Note:X is non fixed character, defined by SENK SEMI naming rules



# **Package Information**

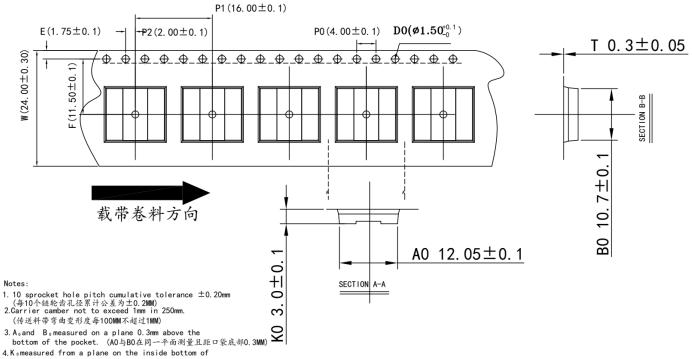
Note: all dimensions are in millimeters.



Symbol	Dimensions Ir	n Millimeters	Dimensions In Inches		
Symbol	Min.	Max.	Min.	Max.	
Α	-	2.650	•	0.104	
A1	0.100	0.300	0.004	0.012	
A2	2.250	2.350	0.089	0.093	
b	0.350	0.450	0.014	0.018	
b1	1.560	1.760	0.061	0.069	
b2	1.770	1.970	0.070	0.078	
С	0.460	0.540	0.018	0.021	
D	10.250	10.350	0.404	0.407	
E	11.650	11.950	0.459	0.470	
E1	7.750	7.850	0.305	0.309	
е	1.270(BSC)		0.050(BSC)		
e1	2.43(BSC)		0.096(BSC)		
e2	2.76(BSC)		0.109	(BSC)	
L	1.090	1.290	0.043	0.051	
θ	1°	5°	1°	5°	



### **Packing information**



the pocket to the top surface of the carrier. (KO为口袋底部与材料表面的平面距离。)

5. All dimensions meet EIA-481-D requirements.

 All dimensions meet EIA-481-D requirements (所有尺寸符合EIA-481-D标准要求。)

6. Material: Black polystyrene

(材料:黑色聚苯乙烯。) 7. Thickness: 0.3 ±0.05 mm.

7. Inickness: 0.3 ±0.05 mm (厚度:0.3±0.05毫米。)

8. Packing length per 22" reel: 200 Meters.

(每个22"卷轴包装长度为 200米。)

9. Component loader per 13" reel: pcs. (每个13"卷轴可装个零件。前后各空 PCS

注:未注明公差为±0.1; F值以B0为中心; P2值以A0为中心.



#### Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

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#### **Revision History**

Revision	Change	Page	Author	Date
1.0	Initial draft	1-25	LEC	2024.04.03
2.0	Add SC8450A1FT-150F3、SC8460A1FT-150F5	2	MWJ	2024.07.03