

# Automotive-Grade , Up to150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection

#### Description

The SC8450 series is a new member of SENK SEMI.'s fully integrated current sensor product line, With the industry's first packaging technology, current wire impedance as low as  $0.24m\Omega$  is achieved on a wide-body SOP-16 package of 10mm\*11mm\*2.3mm, It can be used in power systems requiring measurements up to 150A. Suitable for customers for batch automatic patch production, it is the best solution for small volume, high current applications.

The SC8450 series is an isolated current detection chip that operates on the open-loop Hall sensor detection principle. By introducing the current conductor on the high voltage side into the package, based on the magnetic effect of the current, the equal-proportional magnetic field generated around the measured conductor is induced by the magnetic sensor of the built-in chip and converted into the equal-proportional voltage signal that can be processed, The voltage signal is read and amplified by the built-in high-precision ADC, and with digital calibration technology, environmental variables such as temperature, noise, hysteresis, nonlinearity and so on are removed, and the final output voltage value is nearly ideal ratio with the measured current value, so as to achieve isolated current measurement.

The SC8450 series adds built-in and adjustable fault monitoring with an open drain output, and its built-in FLAG\_F uses a built-in fixed fault threshold without requiring any additional components, Built-in protection response of less than 2uS can be achieved, Very suitable for severe short-circuit fault detection. FLAG\_S supports users to set their own fault thresholds using peripheral divider resistors, And the current pulse shielding setting can ignore the interference in the application to prevent false alarms, very suitable for mild overcurrent detection and feedback peak setting. This function is flexible in fault detection and greatly simplifies the circuit board application layout.

#### Features

- AEC-Q100 automotive qualified
- Isolated measurement, isolated voltage up to 4.8kv @50HZ,1min
- Can measure DC, AC current
- Signal detection bandwidth up to 240khz
- Lowest current wire impedance:0.24mΩ
- Differential sensing technology has high anti-interference ability to the external environment
- User configurable fault detection function FLAG\_F: Built-in protection, suitable for severe short circuit detection

FLAG\_S: Adjustable protection for overload detection and user configuration

- Static voltage output support: 0.1VCC/0.5VCC
- Response time as low as 2uS
- Wide range of measured current: 0A~150A

Isolation safety certification:

• High accuracy: Accuracy error < 1% at 25°C

Operating temperature: Accuracy error<3%

- Strong driving capability, supporting output ports with loads as low as 2kΩ
- Independent intellectual property rights, no technology dependence

Certificate Number Estedos Adougul



#### www.senkomicro.com

## Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC



#### **Order information**

Part Number	Characteristics code	Qualified level	Temp Range	Packing	Current IP Range (A)	<b>0AOutput</b> <sup>*1</sup> (V)	Sensitivity *2 (mV/A)	Supply voltag (V)
SC8450A1FT-100B3	-		E( 40, 1250C)	T (Bash 1000	± 100	0.5Vcc	13.2	3.3
SC8450A1FT-150B3					± 150	0.5Vcc	8.8	
SC8450A1FT-50F3					± 50	1.65	26.4	
SC8450A1FB-150F3		Grade 1			± 150	1.65	8.8	
SC8460A1FT-100B5	A	(Aec-Q100)	$\Gamma(-40 \sim 123 \text{ C})$	(Reel, 1000 pieces/reel)	± 100	0.5Vcc	20	
SC8460A1FT-150B5				pieces/ieei)	± 150	0.5Vcc	13.33	
SC8460A1FT-50F5					± 50	2.5	40	5.0
SC8460A1FT-150F5					± 150	2.5	13.33	

Note1: Type B and F Reference output types when IP=0A

В	When IP has no current, VIOUT@0A=VREF=0.5VCC, suitable for bidirectional current detection, zero point and sensitivity
	change with VCC ratio
F	When there is no current in the IP, VIOUT@0A=VREF=2.5V/1.65V, which is suitable for bidirectional current sensing, and the
F	zero point and sensitivity vary with VCC ratio

Note2: Factory shipment default Mask=OuS, this function is turned off, if the customer needs to turn on the function, you can ask our FAE/ agent

#### **Pin Configuration(Top view)**



Pin number	Pin Name	Description
1/2/3/4	IP+	Terminals for current being sampled; fused internally, support connect to 1/2/3/4
5/6/7/8	IP-	Terminals for current being sampled; fused internally, support connect to 5/6/7/8
9	FLAG_F	Built-in fault output, built-in overcurrent threshold multiple
10	VCC	Device power supply terminal
11	VREF	Reference terminal, supporting input and output. Specifically define Note 1 of the above ordering information VIOUT= Vref (IP=0A)
12	VIOUT	Analog output signal, VIOUT=IP*Sens+Vref
13	NC	No connection
14	FLAG_S	Adjustable fault output
15	GND	Signal Ground terminal
16	OC_SET	External fault threshold voltage (support NC)



#### Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### **Thermal Rise vs. Primary Current**

Typical Plastic package temperature[°C] of SC8450/60 vs Primary current [A] based on Demo Board.



#### **Demo Board information**

	DEMO	Units
PCB Layer Number	2	
PCB Copper layer thickness	2	Oz
Total Copper size connected to Primary pins(including all layers)	350	mm <sup>2</sup>
PCB Board Thickness	1.6	mm

#### **Functional Block Diagram**





#### **Absolute Maximum Ratings**

Absolute maximum rating is the operating limit of a device, exceeding which may cause device damage. Frequent operation outside this value range may affect device reliability.

Symbol	Characteristic	Notes	Ratings	Units
Vcc	Supply voltage		6	V
VRCC	Reverse Supply Voltage		-0.1	V
VIOUT	Output Voltage		6	V
Vriout	Reverse Output Voltage	VIOUT, VREF	-0.1	V
VFLAG	Forward Output Voltage	applicable to the ELAC everflow function	6	V
V <sub>RFLAG</sub>	Reverse Output Voltage	applicable to the FLAG overnow function	-0.1	V
Voc_set	Forward Output Voltage	applicable to the OC SET function	6	V
V <sub>ROC_SET</sub>	Reverse Output Voltage	applicable to the OC_SET function	-0.1	V
		Range G	-40~150	
TA	Operating Temperature	Range F	-40~125	°C
		Range E	-40~85	
T <sub>J (max)</sub>	Maximum Junction Temperature		165	°C
T <sub>stg</sub>	Storage Temperature		-65~170	°C
IOUT(Source)	Output Current Source	Shorted Output-to-Ground Current	30	mA
IOUT(Sink)	Output Current Sink	Shorted Output-to-VCC Current	30	mA
IREF(Source)	Vref Current Source	Shorted Vref-to-Ground Current	15	mA
IREF(Sink)	Vref Current Sink	Shorted Vref-to-VCC Current	15	mA
IP <sub>max</sub>	Maximum Continuing IP Current	Based on SENK's Demo Test Board	100	Α
IPover	Transient Over Current at Ambient Temperature	Based on SENK's Demo Test Board, 1pulse, 100ms, 1% Duty Cycle	400	А
ESD	HBM mode	•	4	kV

#### **Isolation Characteristics**

Symbol	Characteristic	Notes	Ratings	Units
V <sub>ISO</sub>	RMS voltage for AC insulation test,50Hz,1min	Agency type-tested for 60 seconds per UL60950-1	4800	Vrms
V <sub>WVRI</sub>	Working Voltage for Basic Isolation	Maximum working voltage according to UL60950-1		V <sub>Peak</sub>
Dcl	Clearance	Minimum distance through air from IP leads to signal leads	8	mm
Dcr	Creepage distance	Minimum distance along package body from IP leads to signal leads	8	mm
CTI	Comparative trackong index	the electrical breakdown (tracking) properties of an insulating material	600	V
VIOSM	Maximum surge isolation voltage	Tested $\pm 5$ pulses at 2/minute in compliance to IEC 61000-4-5 1.2 $\mu$ s (rise) / 50 $\mu$ s (width).	10	kV
I <sub>IOSM</sub>	Maximum Transient impulse current	Tested $\pm 5$ pulses at 3/minute with 8 $\mu$ s (rise) / 20 $\mu$ s (width)	20	kA

Note 1: Meet the safety certification of UL60950-1 and CB62368-1

#### **Reference application Specification**

Symbol	Description	Min	Тур	Max	Unit
Cvcc	The filter capacitor of power supply is connected between VCC and GND	0.1	0.47		uF
CVIOUT	The filter capacitor of Output is connected between Vout and GND		1		nF
CVREF	The filter capacitor of Output is connected between Vref and GND		1		nF
R <sub>FLAG_F</sub>	The pull-up resistence is connected between FLAG_F and VCC		10		kΩ
R <sub>FLAG_S</sub>	The pull-up resistence is connected between FLAG_S and VCC		10		kΩ



#### Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

## **Common Electrical Characteristics**

Note: Over full range of  $T_A=25^{\circ}C$ ,  $C_{Bypass}=0.47 \mu F$ ,  $C_{Load}=1nF$ ,  $V_{CC}=3.3V/5V$ 

Characteristic	Symbol	Test Conditions	Min	Тур	Max	Unit
Supply Voltage	V	Operating, SC8450XXX-XXX3	3	3.3	3.6	V
Supply Voltage	V CC	Operating, SC8460XXX-XXX5	4.5	5.0	5.5	V
Supply Current	I	$V_{CC} = 4.5 \sim 5.5 V$ , output open		22		mA
Supply Current	ICC	$V_{CC} = 3 \sim 3.6 V$ , output open		15		mA
Output Resistive Load	$R_{\rm L}$	Between VIOUT and GND	2			kΩ
VREF Resistive Load	RLREF	Between VREF and GND	2			kΩ
Anti-external magnetic interference suppression ratio	CMFR	The external interference magnetic field perpendicular to the chip surface		-36		dB
Primary Conductor Resistance	R <sub>PRIMARY</sub>	$T_A = 25^{\circ}C$		0.24		mΩ
Temperature Coefficient of Primary Conductor Resistance	TC <sub>R</sub>	T <sub>A</sub> =-40~125°C		3421		ppm/°C
Hysteresis Voltage	$V_{hys}$	Viout(IP to +40A then return to 0A)- Viout(IP to -40A,then return to0A)		1		mV
Rise time	tr	IP=50A/uS		2.08		uS
Propagation Delay	t <sub>pd</sub>	IP=50A/uS		1.15		uS
Response Time	tresponse	IP=50A/uS		1.82	2	μS
Bandwidth	f	Small-signal –3 dB,		240		kHz
		BW=240KHz		38.7		mA(rms)
Noise	I <sub>N</sub>	BW=10KHz		6		mA(rms)
		BW=1KHz		2		mA(rms)
Nonlinearity	E <sub>LIN</sub>	-100A <ip<100a< td=""><td></td><td></td><td>1</td><td>%</td></ip<100a<>			1	%
Bidirectional Quiescent Output(suitable for product with suffix B3)	$\mathbf{S}_{\mathrm{coef}}$	VCC=3.3V, S <sub>coef</sub> =Sens(VCC)/Sens(3.3V)		VCC/3.3		
Bidirectional Quiescent Output(suitable for product with suffix B5)	$S_{\rm coef\_B5}$	VCC=5.0V, S <sub>coef</sub> =Sens(VCC)/Sens(5V)		VCC/5		
VIOUT Linear Rail to Rail Output Range	Vrail-rail	$R_L=4.7k\Omega$	10		90	%VCC
Power-On Time	t <sub>PO</sub>	Output reaches steady state level, $T_J = 25^{\circ}C$		150		μS



#### Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### FLAG overcurrent detection of electrical parameters

Note1: Over full range of TA=25°C,  $C_{Bypass}$ =0.47 $\mu$ F,  $C_{Load}$ =1.0nF,  $R_{pu}$ =10 $k\Omega$ ,  $V_{CC}$ =3.3/5V

Note 2: Whether FLAG\_S or FLAG\_F sets the trigger threshold current, it is recommended that the actual loaded effective current is 1.15\*IFLAG

Characteristic	Symbol	Test Conditions	Min	Тур	Max	Unit		
Overcurrent detection of electrical parameters								
OC_SET external input range	Voc_set	OC_SET input voltage	0		Vcc	V		
OC_SET PIN input current	I <sub>IN</sub>	High impedance, pin input current			8	uA		
Fault output low voltage	V <sub>FLAG</sub>	$R_{PU}=10k\Omega$	0		0.5	V		
FLAG_F built-in fault range	$I_{FLAG\ (F)}$	Supported built-in multiples ( $I_{PR}$ =peak current) , See the corresponding model Settings for details		0.75*IPR~2 *IPR		А		
		$OC\_SET \in (0.3*Vcc, 0.34*Vcc)$		IPR*0.75		А		
		$OC\_SET \in (0.41*Vcc, 0.45*Vcc)$		IPR*1		А		
FLAG_S adjustable fault	т	$OC\_SET \in (0.55*Vcc, 0.59*Vcc)$		IPR*1.25		А		
range <sup>[1]</sup>	IFLAG (S)	$OC\_SET \in (0.65*Vcc, 0.71*Vcc)$		IPR*1.5		А		
		$OC\_SET \in (0.79*Vcc, 0.83*Vcc)$		IPR*1.75		А		
		$OC\_SET \in (0.91*Vcc, 0.97*Vcc)$		IPR*2		А		
FLAG_F restore the threshold point <sup>[2]</sup>	_	Current drops to IRE until VFLAG returns to high		50%*I <sub>FLAG</sub>		А		
FLAG_S restore the threshold point <sup>[2]</sup>	IRE	level		50%*I <sub>FLAG</sub>		А		
FLAG_F back difference value	I			50% *I <sub>FLAG</sub>		А		
FLAG_F back difference value	IHYS	IHYS=  IFLAG-IRE		50% *I <sub>FLAG</sub>		А		
	Dy	namic response characteristics of overcurrent	detection			r		
fault clearance time	T <sub>CF</sub>	The time from the IP address falling below IFLAG-IHYs to the time when VFLAG is pulled above VFLAG; $R_{PU}=10 \text{ k}\Omega$		3		uS		
FLAG output response time	T <sub>R</sub>	$R_{PU}=10k\Omega$ When the current step jumps to IFLAG*1.15, the response time between FLAG < VFLAG		1.5	2	uS		
FLAG_F output hold time [4]	Thold (FLAG_F)	FLAG_F output continues to pull down time		10		uS		
Extra duration of current [4]	T <sub>MASK</sub> (FLAG_S)	There must be time to determine the fault and reduce interference and false triggering		3		uS		
FLAG_S output hold time <sup>[4]</sup>	THOLD (FLAG_S)	FLAG_S output continues to pull down time		10		uS		

[1] The relationship between the threshold setting of FLAG\_S and the overcurrent trigger point is set in STEP mode to prevent false trigger. The overcurrent trigger point is determined by the voltage obtained by OC\_SET, not the resistance value, as described in the section "OC\_SET Pin Relationship with FLAG\_S".

[2] If the absolute value of the IP is higher than IFLAG (S) or IFLAG (F), the internal fault comparator will trip. The IP must be lower than the IRE before the internal fault comparator will reset.

[3] Response time: It is recommended to obtain the response time <1.5uS when the actual loading current is IFLAG\*1.15

[4] In order to ignore the false triggering of the interference current pulse in the application, the FLAG\_S trigger condition requires that the primary input current should remain 3uS after the Tr time, which can be simply understood as the total duration of the primary current:  $Tr+T_{MASK}$ 

[4] Factory shipment defaultMask=0uS, The function is disabled

[2/3/4] Design guarantee

# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8450A1FT-100B3 Individual Performance Characteristics

Note: Over full range of  $T_A = -25^{\circ}C$ ,  $C_{Bypass} = 0.47 uF$ ,  $C_{Load} = 1nF$ ,  $V_{CC} = 3.3V$ 

Parameter	Symbol	Test Conditions	Min	$Typ^{[1]}$	Max	Unit		
NOMINAL PERFORMANCE (Regardless of life time drift error )								
Current-Sensing Range	Ipr		-100		100	Α		
IP=0A, VIOUT output	V	IP=0A		0.51/		V		
voltage	VOQ			0.3 VCC				
VREF output voltage	Vref	Independent of the IP input current		0.5V <sub>CC</sub>		V		
Sensitivity	Sens	-100A <ip<100a< td=""><td></td><td>13.2</td><td></td><td>mV/A</td></ip<100a<>		13.2		mV/A		
Built-in flow threshold	FLAG	Built-in overcurrent threshold (Built-in 10)		125		А		
range	ΓLAU(IF)							
Low speed overflow	FLAG	$Min=I_{PR} *0.75$ , $Max=I_{PR} *2$	75		200	Α		
threshold range <sup>[2]</sup>	TLAG (IS)							
		ACCURACY PERFORMANCE						
	Esens	$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%		
Sensitivity Error		$I_{PR} = \pm 100 \text{ A}, T_A = 25 \sim 125 ^{\circ}\text{C}$		±2.5		%		
		$I_{PR} = \pm 100 \text{ A}, T_A = -40 \sim 25^{\circ} \text{C}$		±2.5		%		
	Evoq	$I_{P}=0A, T_{A}=25^{\circ}C$		±12		mV		
Single output zero error		$I_P=0A, T_A=25\sim125^{\circ}C$		±15		mV		
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV		
Differential Output game		$I_{P}=0A, T_{A}=25^{\circ}C$		±10		mV		
Error	Evoe	$I_P=0A, T_A = 25 \sim 125 \circ C$		±15		mV		
Eno		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV		
TOTAL	<b>OUTPUT ERRO</b>	R COMPONENTS : ETOT = {[VIOUT_ideal(IPR)-	-VIOUT(IPR)]/[	Sens <sub>idea</sub> l*I <sub>PR</sub> ]	}*100%			
		$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ} \text{C}$		±1.5		%		
Total Output Error	Etot	$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ} \text{C} \sim 125^{\circ} \text{C}$		±2		%		
_		$I_{PR} = \pm 100 \text{ A}, T_A = -40^{\circ}\text{C} \sim 25^{\circ}\text{C}$		±3		%		
		Accuracy of overcurrent fault threshol	d	•				
Duilt in fault autout	F	$T_A = 25^{\circ}C$		±15		%		
Built-in fault output	LIFLAG_F	$T_{A} = -40^{\circ}C \sim 125^{\circ}C$		±25		%		
		I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%		
Adjustable fault output	EIFLAG_S	IPR *2, TA=-40°C~125°C		±25		%		

[1] The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range



## Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8450A1FT-150B3 Individual Performance Characteristics

Note: Over full range of  $T_A = -25^{\circ}C$ ,  $C_{Bypass} = 0.47 uF$ ,  $C_{Load} = 1nF$ ,  $V_{CC} = 3.3V$ 

Parameter	Symbol	Test Conditions	Min	$Typ^{[1]}$	Max	Unit		
NOMINAL PERFORMANCE (Regardless of life time drift error )								
Current-Sensing Range	I <sub>PR</sub>		-150		150	Α		
IP=0A, VIOUT output	V	ID-04		0.51/		V		
voltage	VOQ	IP=0A		0.3 VCC				
VREF output voltage	Vref	Independent of the IP input current		0.5Vcc		V		
Sensitivity	Sens	-150A <ip<150a< td=""><td></td><td>8.8</td><td></td><td>mV/A</td></ip<150a<>		8.8		mV/A		
Built-in flow threshold	FLAG(IF)	Built-in overcurrent threshold (Built-in 10)		187.5		Α		
range								
Low speed overflow	FLAG (IS)	$Min=I_{PR} *0.75$ , $Max=I_{PR} *2$	112.5		300	Α		
threshold range <sup>[2]</sup>								
		ACCURACY PERFORMANCE	1	1	1	т		
		$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%		
Sensitivity Error	Esens	$I_{PR} = \pm 150 \text{ A}, T_A = 25 \sim 125^{\circ}\text{C}$		±2		%		
		$I_{PR} = \pm 150 \text{ A}, T_A = -40 \sim 25^{\circ} \text{C}$		±2.5		%		
	Evoq	$I_P=0A, T_A=25^{\circ}C$		±10		mV		
Single output zero error		$I_P=0A, T_A=25\sim125^{\circ}C$		±15		mV		
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV		
Differential Output zero	Evoe	$I_P=0A, T_A=25^{\circ}C$		±10		mV		
Error		$I_P=0A, T_A=25\sim125^{\circ}C$		±15		mV		
EII0		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV		
TOTAL	OUTPUT ERRO	R COMPONENTS : ETOT = {[VIOUT_ideal(IPR)	-VIOUT(IPR)]/	[Sens <sub>idea</sub> l*I <sub>PR</sub> ]	}*100%			
		$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ} \text{C}$		±2		%		
Total Output Error	Etot	$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ} \text{C} \sim 125^{\circ} \text{C}$		±2		%		
		$I_{PR} = \pm 150 \text{ A}, T_A = -40^{\circ}\text{C} \sim 25^{\circ}\text{C}$		±3		%		
		Accuracy of overcurrent fault threshol	d	<u> </u>	•			
Duilt in foult output	Б	$T_A = 25^{\circ}C$		±15		%		
Built-III fault output	CIFLAG_F	$T_A = -40^{\circ}C \sim 125^{\circ}C$		±25		%		
		$I_{PR} *2, T_A=25^{\circ}C$		±15		%		
Adjustable fault output	EIFLAG_S	IPR *2. TA=-40°C~125°C		±25		%		

[1] The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8450A1FT-50F3 Individual Performance Characteristics

Note: Over full range of  $T_A = -25^{\circ}C$ ,  $C_{Bypass} = 0.47 \mu F$ ,  $C_{Load} = 1 nF$ ,  $V_{CC} = 3.3 V$ 

Parameter	Symbol	Test Conditions	Min	$Typ^{[1]}$	Max	Unit		
NOMINAL PERFORMANCE (Regardless of life time drift error )								
Current-Sensing Range	Ipr		-50		50	Α		
IP=0A, VIOUT output	Voo	IP=0A		1.65		V		
voltage								
VREF output voltage	Vref	Independent of the IP input current		1.65		V		
Sensitivity	Sens	-50A <ip<50a< td=""><td></td><td>26.4</td><td></td><td>mV/A</td></ip<50a<>		26.4		mV/A		
Built-in flow threshold	FLAG(IF)	Built-in overcurrent threshold (Built-in 10)		62.5		А		
Low speed overflow threshold range <sup>[2]</sup>	FLAG (IS)	Min=I <sub>PR</sub> *0.75, Max= I <sub>PR</sub> *2	37.5		100	A		
<u>z</u>		ACCURACY PERFORMANCE			•	·		
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%		
Sensitivity Error	Esens	$I_{PR} = \pm 50 \text{ A}, T_A = 25 \sim 125 ^{\circ}\text{C}$		±2		%		
		$I_{PR} = \pm 50 \text{ A}, T_A = -40 \sim 25^{\circ} \text{C}$		±2.5		%		
	Evoq	$I_P=0A, T_A=25^{\circ}C$		±10		mV		
Single output zero error		$I_P=0A, T_A=25\sim125^{\circ}C$		±15		mV		
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV		
Differential Output zero	Evoe	$I_P=0A, T_A=25^{\circ}C$		±10		mV		
Error		$I_P=0A, T_A = 25 \sim 125^{\circ}C$		±15		mV		
Enor		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV		
TOTAL	OUTPUT ERRO	<b>R</b> COMPONENTS : ETOT = {[VIOUT_ideal(IPR)	-VIOUT(IPR)]/	[Sens <sub>idea</sub> l*I <sub>PR</sub> ]	}*100%			
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ} \text{C}$		±2		%		
Total Output Error	Etot	$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ} \text{C} \sim 125^{\circ} \text{C}$		±2		%		
		$I_{PR} = \pm 50$ A, $T_A = -40^{\circ}C \sim 25^{\circ}C$		±3		%		
		Accuracy of overcurrent fault threshol	d		-			
Built-in fault output	Errice	$T_A = 25^{\circ}C$		±15		%		
Built-in fault output	LIFLAG_F	T <sub>A</sub> = -40°C~125°C		±25		%		
A divertable fault outrast	<b>D</b>	I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%		
Aujustable fault output	EIFLAG_S	IPR *2. $T_{A}=-40^{\circ}C\sim125^{\circ}C$		±25		%		

[1] The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8460A1FT-50F5 Individual Performance Characteristics

Note: Over full range of  $T_A = -25^{\circ}C$ ,  $C_{Bypass} = 0.47 \mu F$ ,  $C_{Load} = 1 nF$ ,  $V_{CC} = 3.3 V$ 

Parameter	Symbol	Test Conditions	Min	$Typ^{[1]}$	Max	Unit	
NOMINAL PERFORMANCE (Regardless of life time drift error)							
Current-Sensing Range	IPR		-50		50	Α	
IP=0A, VIOUT output	Vee	10-04		2.5		V	
voltage	VOQ	IF-0A		2.5			
VREF output voltage	Vref	Independent of the IP input current		2.5		V	
Sensitivity	Sens	-50A <ip<50a< td=""><td></td><td>40</td><td></td><td>mV/A</td></ip<50a<>		40		mV/A	
Built-in flow threshold	FLAG(IF)	Built-in overcurrent threshold (Built-in 10)		62.5		А	
range							
Low speed overflow	FLAG (IS)	$Min=I_{PR} * 0.75$ , $Max=I_{PR} * 2$	37.5		100	Α	
threshold range <sup>[2]</sup>							
		ACCURACY PERFORMANCE	•	•			
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%	
Sensitivity Error	Esens	$I_{PR} = \pm 50 \text{ A}, T_A = 25 \sim 125 ^{\circ}\text{C}$		±2		%	
		$I_{PR} = \pm 50 \text{ A}, T_A = -40 \sim 25^{\circ} \text{C}$		±2.5		%	
	Evoq	$I_{P}=0A, T_{A}=25^{\circ}C$		±10		mV	
Single output zero error		$I_P=0A, T_A = 25 \sim 125 \circ C$		±15		mV	
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV	
Differential Output zero Error	Evoe	$I_P=0A, T_A=25^{\circ}C$		±10		mV	
		$I_P=0A, T_A = 25 \sim 125 \circ C$		±15		mV	
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV	
TOTAL	TOTAL OUTPUT ERROR COMPONENTS : ETOT = {[VIOUT_ideal(IPR)-VIOUT(IPR)]/[Sensideal*IPR]}*100%						
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ} \text{C}$		±2		%	
Total Output Error	Etot	$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ} \text{C} \sim 125^{\circ} \text{C}$		±2		%	
		$I_{PR} = \pm 50 \text{ A}, T_A = -40^{\circ}\text{C} \sim 25^{\circ}\text{C}$		±3		%	
		Accuracy of overcurrent fault threshol	d		•	. <u>.</u>	
Duilt in fault autout	F	$T_A = 25^{\circ}C$		±15		%	
Built-in fault output	LIFLAG_F	$T_{A} = -40^{\circ}C \sim 125^{\circ}C$		±25		%	
		$I_{PR}$ *2, $T_A=25^{\circ}C$		±15		%	
Adjustable fault output	EIFLAG_S	IPR *2. TA=-40°C~125°C		±25		%	

[1] The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8460A1FT-50B5 Individual Performance Characteristics

Note: Over full range of  $T_A = -25^{\circ}C$ ,  $C_{Bypass} = 0.47 \mu F$ ,  $C_{Load} = 1nF$ ,  $V_{CC} = 3.3V$ 

Parameter	Symbol	Test Conditions	Min	$Typ^{[1]}$	Max	Unit
NOMINAL PERFORMANCE (Regardless of life time drift error)						
Current-Sensing Range	Ipr		-50		50	А
IP=0A, VIOUT output	Voq	IP=0A		0.5Vcc		V
voltage	N/ C			0.51/		17
VREF output voltage	vrei	Independent of the IP input current		0.5 V cc		V
Sensitivity	Sens	-50A <ip<50a< td=""><td></td><td>40</td><td></td><td>mV/A</td></ip<50a<>		40		mV/A
Built-in flow threshold	FLAG(IF)	Built-in overcurrent threshold (Built-in 10)		62.5		A
Low speed overflow threshold range <sup>[2]</sup>	FLAG (IS)	Min=I <sub>PR</sub> *0.75, Max= I <sub>PR</sub> *2	37.5		100	A
		ACCURACY PERFORMANCE	•			
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%
Sensitivity Error	Esens	$I_{PR} = \pm 50 \text{ A}, T_A = 25 \sim 125 ^{\circ}\text{C}$		±2		%
-		$I_{PR} = \pm 50 \text{ A}, T_A = -40 \sim 25^{\circ} \text{C}$		±2.5		%
		$I_P=0A, T_A=25^{\circ}C$		±10		mV
Single output zero error	Evoq	$I_P=0A, T_A=25\sim125^{\circ}C$		±15		mV
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV
Differential Output zero Error	Evoe	$I_P=0A, T_A=25^{\circ}C$		±10		mV
		$I_P=0A, T_A = 25 \sim 125^{\circ}C$		±15		mV
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV
TOTAL OUTPUT ERROR COMPONENTS : ETOT = {[VIOUT_ideal(IPR)-VIOUT(IPR)]/[Sensideal*IPR]}*100%						
		$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ} \text{C}$		±2		%
Total Output Error	Etot	$I_{PR} = \pm 50 \text{ A}, T_A = 25^{\circ} \text{C} \sim 125^{\circ} \text{C}$		±2		%
		$I_{PR} = \pm 50$ A, $T_A = -40^{\circ}C \sim 25^{\circ}C$		±3		%
		Accuracy of overcurrent fault threshol	d			-
Built-in fault output	Err to F	$T_A = 25^{\circ}C$		±15		%
Built-in fault output	LIFLAG_F	T <sub>A</sub> = -40°C~125°C		±25		%
A divertable fault output	<b>E</b>	I <sub>PR</sub> *2, T <sub>A</sub> =25°C		±15		%
Aujustable fault output	t EIFLAG_S	IPR *2. $T_{A}=-40^{\circ}C\sim125^{\circ}C$		+25		%

[1] The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range



## *Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC*

#### SC8460A1FT-100B5 Individual Performance Characteristics

Note: Over full range of  $T_A = -25^{\circ}C$ ,  $C_{Bypass} = 0.47 \mu F$ ,  $C_{Load} = 1nF$ ,  $V_{CC} = 5V$ 

Parameter	Symbol	Test Conditions	Min	<b>Typ</b> <sup>[1]</sup>	Max	Unit
NOMINAL PERFORMANCE (Regardless of life time drift error)						
Current-Sensing Range	Ipr		-100		100	Α
IP=0A, VIOUT output	V	IP=0A		0.51		V
voltage	VOQ			0.5 V CC		
VREF output voltage	Vref	Independent of the IP input current		0.5V <sub>CC</sub>		V
Sensitivity	Sens	-100A <ip<100a< td=""><td></td><td>20</td><td></td><td>mV/A</td></ip<100a<>		20		mV/A
Built-in flow threshold		Built-in overcurrent threshold (Built-in 10)		125		А
range	FLAU(IF)					
Low speed overflow	FLAG (Is)	$Min=I_{PR} * 0.75$ , $Max=I_{PR} * 2$	75		200	Α
threshold range <sup>[2]</sup>	1 L/10 (13)					
	1	ACCURACY PERFORMANCE	T	1	1	T
		$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%
Sensitivity Error	Esens	$I_{PR} = \pm 100 \text{ A}, T_A = 25 \sim 125 ^{\circ}\text{C}$		±2		%
		$I_{PR} = \pm 100 \text{ A}, T_A = -40 \sim 25^{\circ} \text{C}$		±2.5		%
	Evoq	$I_P=0A, T_A=25^{\circ}C$		±12		mV
Single output zero error		$I_P=0A, T_A=25\sim125^{\circ}C$		±15		mV
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV
Differential Output zero	Evoe	$I_P=0A, T_A=25^{\circ}C$		±10		mV
Error		$I_P=0A, T_A=25\sim125^{\circ}C$		±15		mV
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV
TOTAL OUTPUT ERROR COMPONENTS: ETOT = {[VIOUT_ideal(IPR)-VIOUT(IPR)]/[Sensideal*IPR]}*100%						
		$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ} \text{C}$		±1.5		%
Total Output Error	E <sub>TOT</sub>	$I_{PR} = \pm 100 \text{ A}, T_A = 25^{\circ} \text{C} \sim 125^{\circ} \text{C}$		±2		%
		$I_{PR} = \pm 100 \text{ A}, T_A = -40^{\circ}\text{C} \sim 25^{\circ}\text{C}$		±3		%
Accuracy of overcurrent fault threshold						
	Б	$T_A = 25^{\circ}C$		±15		%
Built-III fault output	EIFLAG_F	$T_A = -40^{\circ}C \sim 125^{\circ}C$		±25		%
	Г	$I_{PR}$ *2, $T_A=25^{\circ}C$		±15		%
Adjustable fault output	EIFLAG_S	IPR *2. TA=-40°C~125°C		+25		%

[1] The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range

## Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### SC8460A1FT-150B5 Individual Performance Characteristics

Note: Over full range of  $T_A = -25^{\circ}C$ ,  $C_{Bypass} = 0.47 \mu F$ ,  $C_{Load} = 1 n F$ ,  $V_{CC} = 5 V$ 

参数名称	参数符号	测试条件	最小值	典型值1	最大值	单位
NOMINAL PERFORMANCE (Regardless of life time drift error)						
Current-Sensing Range	I <sub>PR</sub>		-150		150	А
IP=0A, VIOUT output	Voo	IP-0A		0.5Vcc		V
voltage	¥0Q			0.5 VCC		
VREF output voltage	Vref	Independent of the IP input current		0.5Vcc		V
Sensitivity	Sens	-150A <ip<150a< td=""><td></td><td>13.33</td><td></td><td>mV/A</td></ip<150a<>		13.33		mV/A
Built-in flow threshold	FLAG(IF)	Built-in overcurrent threshold (Built-in 10)		187.5		А
range						
Low speed overflow	FLAG (Is)	$Min=I_{PR} * 0.75$ , $Max=I_{PR} * 2$	112.5		300	Α
threshold range <sup>[2]</sup>						
	[	ACCURACY PERFORMANCE	1	1	1	
		$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ}\text{C}$		±1.5		%
Sensitivity Error	Esens	$I_{PR} = \pm 150 \text{ A}, T_A = 25 \sim 125^{\circ}\text{C}$		±2		%
		$I_{PR} = \pm 150 \text{ A}, T_A = -40 \sim 25^{\circ} \text{C}$		±2.5		%
	Evoq	$I_{P}=0A, T_{A}=25^{\circ}C$		±10		mV
Single output zero error		$I_P=0A, T_A=25\sim125^{\circ}C$		±15		mV
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV
Differential Output zero Error	Evoe	$I_P=0A, T_A=25^{\circ}C$		±10		mV
		$I_P=0A, T_A=25\sim125^{\circ}C$		±15		mV
		$I_P=0A, T_A = -40 \sim 25^{\circ}C$		±15		mV
TOTAL OUTPUT ERROR COMPONENTS: ETOT = {[VIOUT_ideal(IPR)-VIOUT(IPR)]/[Sensideal*IPR]}*100%						
		$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ} \text{C}$		±2		%
Total Output Error	Etot	$I_{PR} = \pm 150 \text{ A}, T_A = 25^{\circ} \text{C} \sim 125^{\circ} \text{C}$		±2		%
		$I_{PR} = \pm 150 \text{ A}, T_A = -40^{\circ}\text{C} \sim 25^{\circ}\text{C}$		±3		%
		Accuracy of overcurrent fault threshol	d	<u> </u>	•	
Duilt in foult output	Eiflag_f	$T_A = 25^{\circ}C$		±15		%
Built-III fault output		$T_A = -40^{\circ}C \sim 125^{\circ}C$		±25		%
	Г	$I_{PR}$ *2, $T_A$ =25°C		±15		%
Adjustable fault output	EIFLAG_S	I <sub>PR</sub> *2, T <sub>A</sub> =-40°C~125°C		±25		%

[1] The typical value is +/-1 sigma, and 68.27% of products fall within this range; The maximum/minimum value is +/-3 sigma value, and 99.73% of products fall within this range



# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC





# Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC



*Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC* 



#### **Functional Description**

## Internal Reference Voltage

Vref is always equal to the static bias output value of VIOUT, that is, VIOUT value when IP=0A.

The relationship between VIOUT and Vref obey that following formula:

VIOUT=IP\*Sens+Vref,

When SC84xxAFT\*\*Fx is used, VREF constantly outputs 2.5V/1.65V, And has a driving capacity of more than 30mA; When SC84xxAFT\*\*Bx is used, VREF constantly outputs 0.5VCC, And has a driving capacity of more than 30mA;

# • Overcurrent Function

#### Description:

With two overcurrent fault comparators:

- FLAG\_F: When FLAG\_F pins are pulled up, the default output is high. When the absolute value of the input current exceeds IPR\* multiple, the comparator tripping output is pulled down to low level. This function has a <2uS ultra-fast response time, which is very suitable for detection and verification of short circuit events. The overcurrent must be maintained at least 1uS in order to be detected, and after the detection of the post stage, the output low signal will maintain a residence time of 10uS, so that the controller can easily detect the overcurrent signal.
- FLAG\_S: After FLAG\_S pin is pulled up, the default output is high. When the absolute value of the input current exceeds the set threshold, the comparator tripping output is pulled down to the low level. This function improves the high precision characteristic and is suitable for the detection of overload conditions beyond the range. The overcurrent must be maintained at least 3uS in order to be detected, and after the detection of the post stage, the output low signal will maintain a residence time of 10uS, so that the controller can easily detect the overcurrent signal.

OC\_SET: Allows users to set the FLAG\_S trip threshold through external voltage dividers. The relationship between OC\_SET pins and FLAG\_S is shown in the following table:

#### OC\_SET PIN and FLAG\_S Relationship

OC_SET input voltage <sup>[1]</sup>	IFLAG_S trigger threshold <sup>[2]</sup>		
VCC= 3.3V and 5V	SC8450Axxx-xxBx	SC8460Axxx-xxBx	
$OC\_SET \in (0.3*Vcc, 0.34*Vcc)$	IPR*0.75		А
$OC\_SET \in (0.41*Vcc, 0.45*Vcc)$	IPR*1		А
$OC\_SET \in (0.55*Vcc, 0.59*Vcc)$	IPR*1.25		А
$OC\_SET \in (0.65*Vcc, 0.71*Vcc)$	IPR*1.	5	А
$OC\_SET \in (0.79*Vcc, 0.83*Vcc)$ IPR*1.75		75	А
$OC\_SET \in (0.91*Vcc, 0.97*Vcc)$	IPR*2	2	А

#### *Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC*



#### [1] OC\_SET function:

- OC\_SET input voltage supports 0.3\*VCC~0.97\*VCC range, users can set the overcurrent alarm threshold of FLAG\_S pin through the OC\_SET input voltage (as shown in the above table), the input voltage is allowed to use VCC and resistance partial voltage for adaptive (Figure 1). When the OC\_SET input voltage is in the range of OC\_SET ∈ (0.3\*VCC, 0.34\*VCC), it corresponds to the minimum trigger point IFLAG; when the OC\_SET input voltage is in the range of OC\_SET ∈ (0.91\*VCC, 0.97\*VCC), it corresponds to the maximum trigger point IFLAG.
- 2) OC\_SET input voltage supports 0.3\*VCC~0.97\*VCC range, but it should be noted that it is not a linear selection, but designed into a STEP mode, set into 6 intervals, each interval has an input voltage range to correspond to the IFLAG overcurrent trigger threshold.



Figure 1: OC SET resistor divider

#### [2] IFLAG trigger threshold:

Whether FLAG\_S or FLAG\_F sets the trigger threshold current, it is recommended that the actual loaded effective current is IFLAG\* 1.15



# SENKSEMi X®¥\\$#

#### FLAG output characteristic diagram:







Figure 3: FLAG S timing diagram when Tmsk function is enabled

# Figure2 The fault feature applies to FLAG\_F as well as to FLAG\_S, which is disabled by Tmask

When the current through the IP exceeds the IFLAG threshold, after the Tr delay time, the FLAG\_F fault pin will trip, and the fault will remain active for a period of time until the absolute current is less than the fault threshold (IRE).

# Figure 3 Fault characteristics apply to FLAG S when the Tmask function is enabled

TMASK is defined as the extra time that the primary side current must be present after the Tr time has passed.

As shown in Figure 3, where the width of the first current transient pulse is smaller than TMASK, the purpose is that if a fault occurs, but the fault duration is smaller than TMASK, the device will not report the fault, which can prevent the wrong alarm caused by the interference signal of the transient current pulse.

When the second current pulse exceeds the IFLAG threshold and after a time of  $\geq$ TMASK, the fault is triggered and the output is pulled down, until the absolute current is less than the fault threshold (IRE), the fault will remain active for a period of time until the fault state is over and reset.

#### *Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC*



#### Proportional Coefficient Of Sensitivity

Sensitivity ratio coefficient (sens\_coef), which defines the coefficient proportional to the sensitivity and VCC. The ideal coefficient is 1. If the VCC increases by 10%, the sensitivity will increase by 10%. At this time, the coefficient is 1.1, which means that the sensitivity increases by 10% compared with the ideal proportion. The relationship between the scale coefficient is described by the following equation:

#### $S_{coef}\!\!=\!\!Sens\_coef\!\!=\!\!SENS_{VCC}\!/SENS_{VCCN}$

It is the ratio of the sensitivity SENSVCC under the supply voltage Vcc to the sensitivity SENSVCCN under the rated supply voltage VCCN. Through this value, we can get the sensitivity under any supply voltage.

In ideal situation:



#### Proportional Relationship

Using SC8450\_60\*\*B\*, sensitivity and zero voltage are changing with VCC proportion, zero for the VCC / 2, sensitivity to SENS<sub>VCC</sub>\* Sens\_coef. Using SC8450\_60\*\*F\*, sensitivity and zero voltage are changing with VCC proportion, zero for the 0.1VCC, sensitivity to SENS<sub>VCC</sub>\* Sens\_coef.



#### Impact of External Magnetic Fields

CMFR is used to express the ability of sensor resisting impact of external magnetic fields. The larger the absolute value of CMFR, the stronger the ability to resist external magnetic interference is.

$$CMFR = 20 \lg |\frac{A_{CM}}{Sens/CF}|$$

Where CF is the magnetic field coupling factor of the primary current in the sensor, Sens is the sensor sensitivity, and Sens/CF represents the change ratio of the sensor itself in mv/G.

For example: CMFR= -40dB, Sens = 40 mv/A, CF = 10 G/A, then ACM is 0.04 mv/G.

#### Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC



#### • Delay time t<sub>pd</sub> and Response time t<sub>response</sub>

Both delay time and response time are used to characterize the time difference between primary side and secondary side; The delay time is the time difference when the secondary output reaches 20% of the steady-state output value and the primary output reaches 20% of the steady-state current;

The response time is the time difference when the secondary output reaches 90% of the steady-state output value and the primary output reaches 90% of the steady-state current.

#### Rise Time t<sub>r</sub>

The rising time is used to represent the time difference of the secondary side itself, that is, the time difference between the time when the output of the secondary side reaches 90% of the steady-state output value and 10% of the steady-state output value.

#### Power-On Time tpo

Power-On Time is defined as the time it takes for the output voltage to settle within  $\pm 10\%$  of its steady-state value under an applied magnetic field, after the power supply has reached its minimum specified operating voltage.



#### Thermal resistance R<sub>θJA</sub>

Based on a demo board, the thermal resistance is calculated by measuring the chip top temperature and power value. According to the thermal resistance, the junction temperature can be calculated as a reference. The actual surface temperature measurement value is shown in the relationship between the package temperature and the measured current.

#### $T_J = T_A + (R_{\theta JA} * POWER) = T_A + (R_{\theta JA} * IP^2 * R_{PRIMARY});$

Where T<sub>J</sub> is junction temperature and T<sub>A</sub> is ambient temperature.



#### Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### • Reference application circuit diagram

1. Schematic diagram of connection between SC8450/60 and overcurrent detection



2. SC8450/60 VOUT and VREF Differential application diagram: As below : VIOUT = IP \* Sensitivity \* (5R / R)



KSEMi

Up to 150A, High Accuracy Current Sensor with Adjustable **Over Current Fault Detection Current Sensor IC** 

## **PCB Demo Evaluation Board Layout**



## **Mark Description**



Product Number (Refer to order information)

Note:X is non fixed character, defined by SENK SEMI naming rules

Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

# SENKSEMi X®¥\\$k

#### **Package Information**

Note: all dimensions are in millimeters.





#### Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC

#### **Packing information**



#### Up to 150A, High Accuracy Current Sensor with Adjustable Over Current Fault Detection Current Sensor IC



SENK SEMI. co., Ltd. Reserves the right to make, from time to time, such departures from the detail specifications as may be required to permit improvements in the performance, reliability, or manufacturability of its products. Before placing an order, the user is cautioned to verify that the information being relied upon is current.

SENK SEMI.'s products are not to be used in life support devices or systems, if a failure of an SENK SEMI. Product can reasonably be expected to cause the failure of that life support device or system, or to affect the safety or effectiveness of that device or system.

The information included herein is believed to be accurate and reliable. However, SENK SEMI. Co., Ltd. Assumes no responsibility for its use; nor for any infringement of patents or other rights of third parties which may result from its use.

#### **Revision History**

Revision	Change	Page	Author	Date
1.0	Initial draft	1-25	LEC	2024.04.03
2.0	Add SC8450A1FT-150F3、SC8460A1FT-150F5	2	MWJ	2024.07.03

